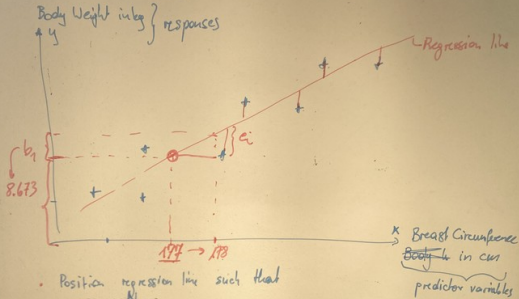


# OHP Picture 1

Recap:

Regression analysis



Position regression line such that

$$e\bar{e} = \sum_{i=1}^n e_i^2 \rightarrow \text{minimal, which gives the least squares condition and yields estimators for}$$

$(b_0)$  and  $(b_1)$   $\rightarrow$  slope of regression line

intercept: crossing between regression line and y-axis

-1065.115

# OHP Picture 2

## Extension of Linear Regression Model

- More than just one "x-variable"
- Example in Exercise 1:

Animal	$x_1$ BC (cm)	$x_2$ BCS (-)	$x_3$ HEI (cm)	$y$ BW (kg)
1	176	5.0	161	471
2				

10

- Are additional x-variables (BCS and HEI) bringing any new information for modelling BW?
- Extended model:
  - $E(y_i) = b_0 + b_1 \cdot x_1 + b_2 \cdot x_2 + b_3 \cdot x_3$
- Estimates for  $b_0, b_1, b_2$  and  $b_3$  are obtained from
$$\left. \begin{array}{l} \frac{\partial \text{SSE}}{\partial b_0} ; \frac{\partial \text{SSE}}{\partial b_1} ; \frac{\partial \text{SSE}}{\partial b_2} ; \frac{\partial \text{SSE}}{\partial b_3} \end{array} \right\} \text{ cumbersome ...}$$

# OHP Picture 3

## Matrix-Vector Notation for Linear Regression

□ All  $x$ -variables are put into Matrix  $X$ :

$$X = \begin{bmatrix} x_{10} & x_{11} & x_{12} \\ x_{20} & x_{21} & x_{22} \\ \vdots & \vdots & \vdots \\ x_{N0} & x_{N1} & x_{N2} \end{bmatrix} \quad N=10$$

columns of all  $x$       BC      HEI

$$x_{10} = x_{20} = \dots = x_{N0} = 1$$

$$y = \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_N \end{bmatrix}, \quad e = \begin{bmatrix} e_1 \\ e_2 \\ \vdots \\ e_N \end{bmatrix}, \quad b = \begin{bmatrix} b_0 \\ b_1 \\ b_2 \end{bmatrix}$$

intercept  
slope for BC  
slope for HEI

response vector  
BIV

□ Regression Model:  $y = X \cdot b + e$  → the same for any number  $N$  and any number  $k$  of variables.

$$\begin{bmatrix} y_1 \\ \vdots \\ y_N \end{bmatrix} = \begin{bmatrix} x_0 & x_{11} & x_{12} \\ \vdots & \vdots & \vdots \\ x_N & x_{N1} & x_{N2} \end{bmatrix} \begin{bmatrix} b_0 \\ b_1 \\ b_2 \end{bmatrix} + \begin{bmatrix} e_1 \\ \vdots \\ e_N \end{bmatrix}$$

$$y_1 = x_{10} \cdot b_0 + x_{11} \cdot b_1 + x_{12} \cdot b_2 + e_1$$

# OHP Picture 4

## Properties of Model in Matrix-vector notation

A expected value of  $y$ :

$$E(y_1) = b_0 + b_1 x_{11} + b_2 x_{12}$$

$$E(y_2) = b_0 + b_1 x_{21} + b_2 x_{22}$$

$$\square \text{ Define } E[y] = \begin{bmatrix} E(y_1) \\ E(y_2) \\ \vdots \\ E(y_n) \end{bmatrix} = \begin{bmatrix} b_0 + b_1 x_{11} + b_2 x_{12} \\ b_0 + b_1 x_{21} + b_2 x_{22} \\ \vdots \\ b_0 + b_1 x_{n1} + b_2 x_{n2} \end{bmatrix} = \begin{bmatrix} x_{10} & x_{11} & x_{12} \\ x_{20} & x_{21} & x_{22} \\ \vdots & \vdots & \vdots \\ x_{n0} & x_{n1} & x_{n2} \end{bmatrix} \begin{bmatrix} b_0 \\ b_1 \\ b_2 \end{bmatrix}$$
$$= X \cdot b$$

$$\square \text{ Verify: } E[y] = E[Xb + e] = E[Xb] + \underbrace{E[e]}_{=0} = E[Xb] + 0$$
$$= E[Xb] = Xb$$

$$\square \text{ Error Terms: } E[e] = 0; \text{ expected value}$$
$$\text{var}(e) = E\left[\underbrace{e - E[e]}_{=0}\right] \left[\underbrace{e - E[e]}_{=0}\right]^T = E[ee^T] = \sigma^2 I_n$$

identity matrix  
with dimension  
 $n \times n$

# OHP Picture 5

- Variance-Covariance Matrix  $\text{var}(e)$

$$\text{var}(e) = \begin{bmatrix} \text{var}(e_1) & \text{cov}(e_1, e_2) & \dots & \text{cov}(e_1, e_n) \\ \text{cov}(e_2, e_1) & \text{var}(e_2) & \dots & \text{cov}(e_2, e_n) \\ \vdots & \vdots & \ddots & \vdots \\ \text{cov}(e_n, e_1) & \text{cov}(e_n, e_2) & \dots & \text{var}(e_n) \end{bmatrix} = \sigma^2 \cdot I_N$$

$$= \begin{bmatrix} \sigma^2 & 0 & 0 & \dots & 0 \\ 0 & \sigma^2 & & & \\ \vdots & & & & \\ 0 & & & & \sigma^2 \end{bmatrix}$$

$\text{var}(e_i) = \sigma^2 \Rightarrow$  where does it come from?

$$\text{cov}(e_i, e_j) = 0 \quad (i \neq j)$$

$\Downarrow$   
estimated from  
data

- From the output of summary from `lm()` in R:

"Residual standard error" is an estimate of  $\sigma$

- $r$  = vector of residuals:

$$\hat{\sigma} = \sqrt{\frac{1}{N-2} r^T r} = \sqrt{\frac{1}{N-2} \sum_{i=1}^N r_i^2}$$

$\downarrow$   
number of parameters  $\Rightarrow b_0, b_1$

## OHP Picture 6

Sum of Squared Residuals in Matrix-Vector Notation

$$\square e^T e = \underbrace{[y - Xb]^T}_{\text{row}} \cdot \underbrace{[y - Xb]}_{\text{column}} = y^T y -$$

$$\square \text{Model: } y = Xb + e \Rightarrow e = y - Xb$$