#### Fixed Linear Effects Models

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### **Background**

- $\triangleright$  Given a population of N animals
- $\triangleright$  Each animal has information on genotypes at loci G, H and I
- $\blacktriangleright$  Each animal has an observation for one quantitative trait of interest y
- **Goal:** Predict genomic breeding values

Data

**Observations** 



#### Two Types Of Models

- 1. **Genetic** Model: How can we decompose the phenotype into genetic part and non-genetic environmental part
- 2. **Statistical** Model: How to estimate unknown parameters from a dataset

#### **Goals**:

- 1. Use genetic model to show how observations and genetic information can be used to predict breeding values.
- 2. Use statistical techniques to do the prediction

#### Genetic Model

 $\triangleright$  simple model from quantitative genetics to split phenotypic observation into

requestion part  $g$  and

 $\blacktriangleright$  environmental part  $e$ 

$$
y=g+e
$$

- $\blacktriangleright$  environment: split into
	- **I** known environmental factors: herd, year, ...  $(\beta)$
	- **In unknown random error**  $(\epsilon)$
- $\triangleright$  polygenic model: use a finite number of loci to model genetic part of phenotypic observation

# Genetic Model (II)



#### Phenotype

#### Polygenic Model

 $\triangleright$  Component g can be decomposed into contributions  $g_i$  of single loci

$$
g=\sum_{j=1}^k g_j
$$

- Assume that loci are additive, hence genotypic values  $g_i$ depends on  $a_i$  with  $d_i = 0$
- ► Genotypic values at locus *j* can either be  $-a_j$ , 0 or  $a_j$
- Breeding values based on locus *j* depends on  $a_j$ .

Genotypic value  $g_i$  for animal *i* over all loci

$$
g_i = M_i \cdot a
$$

where M i is a row vector with elements  $-1$ , 0 and 1 and a is the vector of all genotypic values of the positive homozygous genotypes of all loci.

#### Phenotypic Value

 $\triangleright$  Collecting all components for an observation  $y_i$  for animal i

$$
y_i = W_i \cdot \beta + M_i \cdot a + \epsilon_i
$$

 $\blacktriangleright$  all animals in the population

$$
y = W \cdot \beta + M \cdot a + \epsilon
$$
  
\n
$$
\blacktriangleright \text{ combining } b^T = \left[ \begin{array}{cc} \beta & a \end{array} \right] \text{ and } X = \left[ \begin{array}{cc} W & M \end{array} \right]
$$
  
\n
$$
y = X \cdot b + \epsilon
$$

#### Statistical Model

- $\blacktriangleright$  genetic model from statistics point of view
- $\triangleright$  phenotypic observation as response y
- $\triangleright$  vector b (known environment and genotypic values) as unknown parameter
- $\blacktriangleright$  fixed predictor variales in matrix X
- riangleright vector  $\epsilon$  as random error terms
- $\rightarrow$  Fixed Linear Effects Model

#### Parameter Estimation

- $\blacktriangleright$  use regression model
- $\blacktriangleright$  regression means both response and predictors are continuous
- $\blacktriangleright$  example dataset: body weight on breast circumference

# Regression Dataset



#### Regression Model

- response  $y$ : body weight
- $\blacktriangleright$  predictor x: breast circumference
- $\triangleright$  model for observation  $v_i$

$$
y_i = x_i * b + \epsilon_i
$$

- **If** meaning of b: change  $x_i$  by one unit  $\rightarrow y_i$  changes on average by *b* units.
- ightharpoonup use case: measure  $x_{N+1}$  for animal  $N+1$  with unknown weight and use b to predict  $y_{N+1}$

### Least Squares

- $\blacktriangleright$  How to find b such that y is best approximated by x
- Residuals  $r_i = y_i x_i * \hat{b}$
- $\triangleright$  Minimization of sum of squared residuals (LS)
- ► Use  $\hat{b}$  at minimal LS as estimate

# LSQ Diagram



#### Sum of squared residuals

$$
LS = \sum_{i=1}^{n} r_i^2
$$

 $-$  In matrix-vector notation with  $r$  denoting the vector of all residuals

$$
LS = ||r||^2 = r^T r
$$

where ||*.*|| stands for the norm ("length in 2D") of a vector

$$
\blacktriangleright
$$
 Replacing *r* with  $r = y - X\hat{b}$ 

$$
LS = (y - X\hat{b})^{\mathsf{T}}(y - X\hat{b}) = y^{\mathsf{T}}y - y^{\mathsf{T}}X\hat{b} - \hat{b}^{\mathsf{T}}X^{\mathsf{T}}y + \hat{b}^{\mathsf{T}}X^{\mathsf{T}}X\hat{b}
$$

#### Minimization

Set partial derivative of LS with respect to  $\hat{b}$  to 0

$$
\frac{\partial LS}{\partial \hat{b}} = -X^{\mathsf{T}}y - X^{\mathsf{T}}y + 2X^{\mathsf{T}}X\hat{b} = 0
$$

 $\triangleright$  Take the  $\hat{b}$  that satisfies the above equation as the least squares estimate  $\hat{b}_{LS}$ 

$$
X^T X \hat{b}_{LS} = X^T y
$$



$$
\hat{b}_{LS} = (X^TX)^{-1}X^Ty
$$

#### Variance of Error Terms

**I** Least Squares Procedure does not yield an estimate for  $\sigma^2$  $\blacktriangleright$  The estimator based on the residuals

$$
\hat{\sigma^2} = \frac{1}{n-p} \sum_{i=1}^n r_i^2
$$

Different Types of Regressions

 $\blacktriangleright$  Regression through the origin

$$
y_i = x_i * b + e_i
$$



$$
y_i = b_0 + x_i * b + e_i
$$

#### **Predictions**

▶ One of the use-cases for regression is **prediction**  $\blacktriangleright$  Prediction means that given a regression model with estimated regression coefficients based on a data set, values of responses are to be predicted for new predictor values  $(x_{new})$ 

$$
\hat{y} = x_{new} * \hat{b}
$$

ightharpoonup Mo predictions outside of the range of x used to estimate  $\hat{b}$ 

#### Multiple Linear Regression

- $\triangleright$  Use more than one predictor variable
- Example: Conformation traits BCS and HEI besides BC
- $\blacktriangleright$  New model:

$$
y_i = b_0 + BC_i * b_1 + BCS_i * b_2 + HEI_i * b_3 + e_i
$$

 $\blacktriangleright$  In matrix vector notation:

$$
y = Xb + \epsilon
$$
 with 
$$
b^T = \left[\begin{array}{cccc} b_0 & b_1 & b_2 & b_3 \end{array}\right]
$$

#### New data set

Animal	<b>Breast Circumference</b>	Body Weight	<b>BCS</b>	HEI
1	176	471	5.0	161
2	177	463	4.2	121
3	178	481	4.9	157
4	179	470	3.0	165
5	179	496	6.8	136
6	180	491	4.9	123
7	181	518	4.4	163
8	182	511	4.4	149
9	183	510	3.5	143
10	184	541	4.7	130

Table 2: Dataset for Multiple Linear Regression

#### Goal

- Find solution for  $\hat{b}_{LS}$
- $\triangleright$  Same principle of least squares as with simple linear regression
- $\triangleright$  Different dimensions for X and b
- $\rightarrow$  Problem 1 in Exercise 2

#### Regression on Dummy Variables

- $\triangleright$  What happens when predictor variables X are no longer continuous
- $\blacktriangleright$  Examples: SNP-Genotypes
- I X can only take a few discrete values, e.g., 0*,* 1 or −1*,* 0*,* 1, . . .

 $\rightarrow$  regression on dummy variables or just general fixed linear model.

# Example: SNP-Data



#### Goal

- $\triangleright$  Same as in linear regression: fit line through points such that least squares criterion holds
- $\blacktriangleright$  Interpretation: Difference between effect levels
- $\blacktriangleright$  For SNP-data: differences correspond to marker effects

### Dummy Regression Line



#### Problem

- In many datasets X does not have full column-rank  $\blacktriangleright$  That means some columns of X show linear dependence
- As a consequence of that  $(X^TX)$  cannot be inverted

#### Solution

- ▶ Use a generalised inverse  $(X^TX)^-$  to get a solution  $\hat{b}_{LS}$  for least squares normal equations
- ▶ Use estimable functions of  $\hat{b}_{LS}$  which are independent of the choice of  $(X^TX)^-$
- $\triangleright$  One example for estimable functions are differences between effect levels
- $\triangleright$  For example of SNP-data these correspond to marker effects.

#### Generalised Inverse

- Reminder: the (ordinary) inverse  $A^{-1}$  of A is given by  $A^{-1}A = I$ , but  $A^{-1}$  exists only, if  $A$  is of full rank.
- A generalised inverse G of matrix A satisfies:  $AGA = A$
- For the system of equations  $Ax = y$ , the vector  $x = Gy$  is a solution, if  $AGA = A$
- $\triangleright$  For a generalised inverse G of A, the system of equation  $Ax = y$  has solutions

$$
\tilde{x} = Gy + (GA - I)z
$$

for an arbitrary vector z.

ighthrow linear function of the parameter  $(b)$  that is identical to linear function of expected values of observations y, i.e.,

$$
q^T b = t^T E(y)
$$

 $\triangleright$  estimable functions are invariant (do not change) with different generalised inverses.