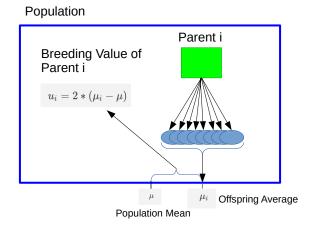
Prediction of Breeding Values

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What are breeding values

Definition: two times difference between offspring of a given parent from population mean



Practical Considerations

- Definition of breeding value is based on biological fact that parent passes half of its alleles to offspring
- In practice, definition cannot be used
 - most parents do not have enough offspring
 - breeding values are needed before animals have offspring
 - different environmental factors not considered

Solution

- Use genetic model to predict breeding values based on phenotypic observations
- Genetic model decomposes phenotypic observation (y_i) in different components

$$y_i = \mu + u_i + d_i + i_i + e_i$$

where μ is the general mean, u_i the breeding value, d_i the dominance deviation, i_i the epistasis effect and e_i the random error term.

Solution II

For predicting breeding values d_i and i_i are often ignored, leading to a simplified version of the genetic model

$$y_i = \mu + u_i + e_i$$

Expected values and variance-covariance matrix

$$E\begin{bmatrix} y_{i}\\ u_{i}\\ e_{i} \end{bmatrix} = \begin{bmatrix} \mu\\ 0\\ 0 \end{bmatrix}$$
$$var\begin{bmatrix} y_{i}\\ u_{i}\\ e_{i} \end{bmatrix} = \begin{bmatrix} \sigma_{y}^{2} & \sigma_{u}^{2} & \sigma_{e}^{2}\\ \sigma_{u}^{2} & \sigma_{u}^{2} & 0\\ \sigma_{e}^{2} & 0 & \sigma_{e}^{2} \end{bmatrix}$$

How to Predict Breeding Values

- Predicted breeding values (û) are a function of the observed phenotypic data (y)
- $\rightarrow \hat{u} = f(y)$
 - ▶ What should *f*() look like?
 - Goal: Maximize improvement of offspring generation over parents

 $\rightarrow \hat{u}$ should be conditional expected value of true breeding value u given y:

$$\hat{u} = E(u|y)$$

Derivation

Assume: multivariate normality of u and y and E(u) = 0, then

$$\hat{u} = E(u|y) = E(u) + cov(u, y^T) * var(y)^{-1} * (y - E(y))$$

= $E(u|y) = cov(u, y^T) * var(y)^{-1} * (y - E(y))$

- \hat{u} consists of two parts
- 1. (y E(y)): phenotypic observations corrected for environmental effects
- 2. $cov(u, y^T) * var(y)^{-1}$: weighting factor of corrected observation

Unbiasedness

Expected value $(E(\hat{u}))$

$$E(\hat{u}) = E(cov(u, y^{T}) * var(y)^{-1} * (y - E(y)))$$

= cov(u, y^{T}) * var(y)^{-1} * E(y - E(y))
= cov(u, y^{T}) * var(y)^{-1} * (E(y) - E(y)) = 0

• With E(u) = 0, it follows $E(\hat{u}) = E(u) = 0$

Variance

• $var(\hat{u})$ and $cov(u, \hat{u})$ important for quality of prediction

$$var(\hat{u}) = var(cov(u, y^{T}) * var(y)^{-1} * (y - E(y)))$$

= $cov(u, y^{T}) * var(y)^{-1} * var(y - E(y))$
* $var(y)^{-1} * cov(y, u^{T})$
= $cov(u, y^{T}) * var(y)^{-1} * cov(y, u^{T})$
 $cov(u, \hat{u}) = cov(u, (cov(u, y^{T}) * var(y)^{-1} * (y - E(y)))^{T})$
= $cov(u, (y - E(y))^{T}) * var(y)^{-1} * cov(y, u^{T})$
= $cov(u, y^{T}) * var(y)^{-1} * cov(y, u^{T}) = var(\hat{u})$

Accuracy

Measured by r_{u,û}
 Recall cov(u, û) = var(û)

$$r_{u,\hat{u}} = \frac{cov(u,\hat{u})}{\sqrt{var(u) * var(\hat{u})}}$$
$$= \sqrt{\frac{var(\hat{u})}{var(u)}}$$

• Reliability ("Bestimmtheitsmass"): $B = r_{u,\hat{u}}^2$

Prediction Error Variance (PEV)

• Variability of prediction error: $u - \hat{u}$

$$var(u - \hat{u}) = var(u) - 2cov(u, \hat{u}) + var(\hat{u}) = var(u) - var(\hat{u})$$
$$= var(u) * \left[1 - \frac{var(\hat{u})}{var(u)}\right]$$
$$= var(u) * \left[1 - r_{u,\hat{u}}^{2}\right]$$

Obtained from coefficient matrix of mixed model equations
 Used to compute reliability

Conditional Density

- Assessment of risk when using animals with predicted breeding values with different reliabilities quantified by f(u|û)
- Multivariate normal density with mean E(u|û) and variance var(u|û)

$$E(u|\hat{u}) = E(u) + cov(u, \hat{u}^{T}) * var(\hat{u})^{-1} * (\hat{u} - E(\hat{u})) = \hat{u}$$

$$var(u|\hat{u}) = var(u) - cov(u, \hat{u}^{T}) * var(\hat{u})^{-1} * cov(\hat{u}, u^{T})$$

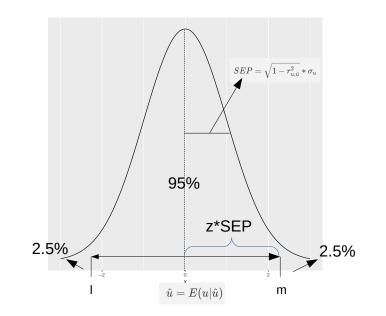
$$= var(u) * \left[1 - \frac{cov(u, \hat{u}^{T})^{2}}{var(u) * var(\hat{u})}\right]$$

$$= var(u) * \left[1 - r_{u,\hat{u}}^{2}\right]$$

Confidence Intervals (CI)

- ▶ Assume an error level α , this results in 100 * (1α) %-Cl
- Typical values of α 0.05 or 0.01
- With α = 0.05, the 95%-Cl gives interval around mean which covers a surface of 0.95

CI-Plot



CI Limits

Iower limit I and upper limit m are given by

$$l = \hat{u} - z * SEP$$

$$m = \hat{u} + z * SEP$$
(1)

z corresponds to quantile value to cover a surface of (1 - α)
 Use R-function qnorm() to get value of z

Linear Mixed Effects Model

Use more realistic model for prediction of breeding values

$$y = Xb + Zu + e$$

where

- y vector of length *n* with observations
- *b* vector of length *p* with fixed effects
- *u* vector of length *q* with random breeding values
- *e* vector of length *n* with random error terms
- $X \quad n \times p$ incidence matrix
- $Z \quad n \times q$ incidence matrix

Expected Values and Variances

$$E\begin{bmatrix} y\\ u\\ e \end{bmatrix} = \begin{bmatrix} Xb\\ 0\\ 0 \end{bmatrix}$$
$$var\begin{bmatrix} y\\ u\\ e \end{bmatrix} = \begin{bmatrix} ZGZ^T + R & ZG & 0\\ GZ^T & G & 0\\ 0 & 0 & R \end{bmatrix}$$

Solutions

Same as for simple model

$$\hat{u} = E(u|y) = GZ^T V^{-1}(y - X\hat{b})$$

with

$$\hat{b} = (X^T V^{-1} X)^- X^T V^{-1} y$$

corresponding to the general least squares solution of b

Problem

- Solution for
 û contains V⁻¹ which is large and difficult to compute
- Use mixed model equations

$$\begin{bmatrix} X^{\mathsf{T}}R^{-1}X & X^{\mathsf{T}}R^{-1}Z \\ Z^{\mathsf{T}}R^{-1}X & Z^{\mathsf{T}}R^{-1}Z + G^{-1} \end{bmatrix} \begin{bmatrix} \hat{b} \\ \hat{u} \end{bmatrix} = \begin{bmatrix} X^{\mathsf{T}}R^{-1}y \\ Z^{\mathsf{T}}R^{-1}y \end{bmatrix}$$

Sire Model

$$y = Xb + Zs + e$$

where *s* is a vector of length q_s with all sire effects.

$$var(s) = A_s * \sigma_s^2$$

where A_s : numerator relationship considering only sires

Animal Model

$$y = Xb + Za + e$$

where a is a vector of length q_a containing the breeding values

$$\mathsf{var}(\mathsf{a}) = \mathsf{A}\sigma_\mathsf{a}^2$$

where A is the numerator relationship matrix