

# OHP Picture 1

Recap:

□ Prediction of breeding values

- Regression method:  $\hat{u} = b \cdot (y - \mu)$

$$y = \underbrace{\mu}_{\mu} + \underbrace{u}_{u} + \underbrace{e}_{e}$$

- Different data scenarios:

- 1) own performance
- 2) repeated observation
- 3) offspring: sires used daughters records

□ Problems

- not flexible, cannot use all available observation
- Method that can use all available information

□ Prediction of breeding values follows the same uniform principle:

1. Correction of phenotypes with some suitable population mean. The reason for this is that we have defined breeding values as deviations.
2. Corrected information  $(y - \mu)$  is multiplied by an appropriate factor called  $b$ .

# OHP Picture 2

## Selection Index

- later used to predict aggregate genotype (Genetic advance)
- Generic method useful to combine different sources of information into one summary quantity

□ Before the method BLUP was invented, selection index theory was used to predict breeding values for a single trait.

□ Idea:

- Combines all sources of phenotypic information, e.g.
  - > own performance (own, repeated)
  - > half-sib
  - > full-sib
  - > offspring
  - > parent

- Assume: general principle of prediction:  $\hat{u} = b(y - \mu)$   
 $= by^*$

→ Index of merit I:

$$\begin{aligned} I &= b_1(y_1 - \mu_1) + b_2(y_2 - \mu_2) + \dots + b_k(y_k - \mu_k) \\ &= b_1 y_1^* + b_2 y_2^* + \dots + b_k y_k^* \\ &= b^T y^* \quad (\text{vector-dot product with} \\ &\quad b^T = [b_1 \ b_2 \ \dots \ b_k]; y^* = \begin{bmatrix} y_1^* \\ y_2^* \\ \vdots \\ y_k^* \end{bmatrix}) \end{aligned}$$

# OHP Picture 3

Prediction of breeding value  $u_i$  for animal  $i$  for a single trait:

$$\hat{u}_i = \underline{I} = b^T \cdot y^*$$

with  $y^*$ : vector of all information corrected for appropriate population mean

$b^T$ : vector of unknown index weights

□ Goal:  $\hat{u}_i$  should be such that it predicts  $u_i$  as good as possible  $\Rightarrow$  Error ( $u_i - \hat{u}_i$ ) should be minimal

□ In selection index theory the error is quantified by the prediction error variance:  $\text{var}(u_i - \hat{u}_i)$

$\Rightarrow$  Minimize  $R = \text{var}(u_i - \hat{u}_i)$

$$R = \text{var}(u_i - \hat{u}_i) = \text{var}(u_i - \underline{I}) = \text{var}(u_i - b^T \cdot y^*)$$

$$= \text{var}(u_i) + \text{var}(b^T \cdot y^*) - 2 \text{cov}(u_i, (y^*)^T \cdot b)$$

$$= \sigma_{u_i}^2 + b^T \cdot \text{var}(y^*) \cdot b - 2 b^T \text{cov}(u_i, (y^*)^T)$$

$$\text{var} \begin{pmatrix} y_1^* \\ y_2^* \\ \vdots \\ y_n^* \end{pmatrix} = \begin{bmatrix} \text{var}(y_1^*) & \text{cov}(y_1^*, y_2^*) & \dots \\ \text{cov}(y_2^*, y_1^*) & \text{var}(y_2^*) & \dots \\ \vdots & \vdots & \ddots \end{bmatrix} = P$$

# OHP Picture 4

□ Var of a vector corresponds to a variance-covariance matrix.

Example: vector  $y^* = \begin{bmatrix} y_1^* \\ y_2^* \\ \vdots \\ y_k^* \end{bmatrix}$

$$P = \text{var}(y^*) = \begin{bmatrix} \text{var}(y_1^*) & \text{cov}(y_1^*, y_2^*) & \dots & \text{cov}(y_1^*, y_k^*) \\ \text{cov}(y_2^*, y_1^*) & \text{var}(y_2^*) & \dots & \text{cov}(y_2^*, y_k^*) \\ \vdots & \vdots & \ddots & \vdots \\ \text{cov}(y_k^*, y_1^*) & \text{cov}(y_k^*, y_2^*) & \dots & \text{var}(y_k^*) \end{bmatrix}$$

symmetric matrix  
- it has k rows and k columns

$$\square G = \text{cov}(u, y^*) = \begin{bmatrix} \text{cov}(u, y_1^*) \\ \text{cov}(u, y_2^*) \\ \vdots \\ \text{cov}(u, y_k^*) \end{bmatrix}$$

$$\square R = \sigma_u^2 + b^T P b + 2 b^T G$$

$$\square \text{Minimization: } \frac{\partial R}{\partial b} = 0 = \begin{bmatrix} \frac{\partial R}{\partial b_1} \\ \frac{\partial R}{\partial b_2} \\ \vdots \end{bmatrix}$$

gradient

# OHP Picture 5

□ Minimize  $R$ :

$$R = \mathbf{b}^T \mathbf{P} \mathbf{b} + \mathbf{2b}^T \mathbf{G}$$

$$\frac{\partial R}{\partial \mathbf{b}} = \mathbf{0} + \mathbf{2b}^T \mathbf{P} + \mathbf{2G}^T = \mathbf{0}$$

$$\Leftrightarrow \mathbf{2Pb} - \mathbf{2G} = \mathbf{0}$$

$$\mathbf{Pb} = \mathbf{G}$$

$$\Rightarrow \underbrace{\mathbf{P}^{-1}}_{\mathbf{I}} \mathbf{P} \mathbf{b} = \mathbf{P}^{-1} \mathbf{G}$$

$$\mathbf{b} = \mathbf{P}^{-1} \mathbf{G}$$

because  $\mathbf{P}$  is a variance-covariance matrix, it is positive-definite, i.e. its inverse exist

□ Summary: Selection index theory provides a method to predict breeding values using all available information.

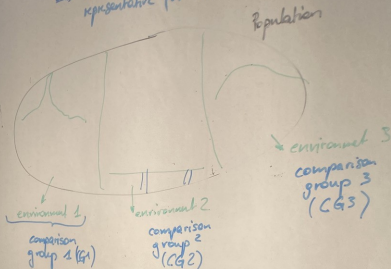
□ Problem: Find appropriate population means to correct phenotypic observations

How to find  $\mu$  such that  $y^* = (y - \mu)$  for all possible data scenarios

□ Requirement for  $\mu$ : Based on model:  $y = \mu + u + e$   
compute average  $\bar{y}$ :  $\bar{y} = \bar{\mu} + \bar{u} + \bar{e}$   
because  $u$  and  $e$  are deviations,  $\bar{u} = \bar{e} = 0$   
 $\Rightarrow \bar{y} = \mu$

# OHP Picture 6

- Aim: To find  $\mu$  such that it is correct in an optimal way for the environment.  
⇒ Form comparison groups that are representative for the environmental conditions.



$$\bar{y}_{CGi} = \mu + \bar{u}_{CGi} + \bar{e}_{CGi}$$
$$\Rightarrow \bar{y}_{CGi} = \mu$$
$$\bar{u}_{CGi} = 0$$
$$\bar{e}_{CGi} = 0$$

$$\left. \begin{array}{l} \text{if } \bar{u}_{CGi} \neq 0 \\ I^* = \hat{u}_i = b(y_i - (\mu + \bar{u}_{CGi})) \\ = b(y_i - \mu_i) - b \bar{u}_{CGi} \\ = \hat{u}_i - \underline{b \bar{u}_{CGi}} \end{array} \right\}$$

Bias

# OHP Picture 7

□ Solution to Bias-Problem in selection index was found when BLUP method was invented:

B: Best → error (prediction error variance) minimal

L: Linear → linear combination of data

U: unbiased → expected value  $E[u] = u$

P: Prediction → Breeding values are treated as random effects, in English/American literature, the term "prediction" is always used for random effects, whereas for fixed effects, the term "estimation" is used ⇒ BLUE

"Vorhersage"

"Schätzung"

Prediction of breeding values (Zuchtwerkselekt)

□ BLUP uses Linear Models

- Simple linear fixed effect model

- Example: In example data set: (Zielgröße)

- > Weaning weight is the response variable (y)

> Herd, Sex, Animal, Sire, dam as predictor variables

(beschreibende Variable)

-  $y_{ij} = \mu + herd_j + e_{ij}$

What is the effect of the herd on the response variable

## OHP Picture 8

- In a fixed linear effect model, only fixed effects can be included. In example:

$$y_{ij} = \mu + \text{herd}_j + e_{ij}$$

- Fit the model to data:

for animal 12:

$$2.61 = \mu + \text{herd}_1 + e_{12,1}$$

15:

$$2.91 = \mu + \text{herd}_2 + e_{15,1}$$

i

27:

$$3.16 = \mu + \text{herd}_2 + e_{27,2}$$

with unknown intercept  $\mu$  and unknown herd effects  $\text{herd}_1$  for herd 1 and  $\text{herd}_2$  for herd 2.

- Result will be find numbers for  $\mu$ ,  $\text{herd}_1$  and  $\text{herd}_2$  such that the sum of the squared residuals ( $e_{ij}$ ) is minimal.  $\Rightarrow$  Least Squares Type of estimation.
- It is not possible to include any variances of an effect into a fixed linear model  
 $\Rightarrow$  Solution are mixed linear effect models (LME)



# OHP Picture 9

□ Mixed linear effect models contain fixed and random effects

□ Example:  $y_{ijk} = \mu + \beta_j + u_i + e_{ijk}$

Annotations:  
-  $\mu$ : intercept  
-  $\beta_j$ : fixed effect of herd  $j$   
-  $u_i$ : random breeding value for animal  $i$   
-  $e_{ijk}$ : random residual  
-  $y_{ijk}$ : observation  $k$  for animal  $i$  in herd  $j$

□ Fit the model to the data:

Animal 12:  $2.61 = \mu + \beta_1 + u_{12} + e_{12,1,1}$

13:  $2.31 = \mu + \beta_1 + u_{13} + e_{13,1,1}$

27:  $3.16 = \mu + \beta_2 + u_{27} + e_{27,2,1}$

Goal: - Estimates for fixed effects  $\beta_1$  and  $\beta_2$

- Predictions for breeding values:  $u_1, \dots, u_{27}$

- Estimate of  $\sigma_u^2$  and  $\sigma_e^2$

→ not possible with least squares

# OHP Picture 10

A Notation for system of equations

- Scalar notation

$$\begin{cases} y_{12,1,1} = \mu + \beta_1 + u_{12} + e_{12,1,1} \\ y_{13,1,1} = \mu + \beta_1 + u_{13} + e_{13,1,1} \\ \vdots \\ y_{27,2,1} = \mu + \beta_2 + u_{27} + e_{27,2,1} \end{cases}$$

- Matrix vector notation:

> combine all observations:  $y_{12,1,1} \dots y_{27,2,1}$   
into a single vector  $y = \begin{bmatrix} y_{12,1,1} \\ y_{13,1,1} \\ \vdots \\ y_{27,2,1} \end{bmatrix}$

> fixed effects in vector  $\beta = \begin{bmatrix} \beta_1 \\ \beta_2 \end{bmatrix}$

> random breeding values  $u = \begin{bmatrix} u_1 \\ u_2 \\ \vdots \\ u_{27} \end{bmatrix}$

> random error terms  $e = \begin{bmatrix} e_{12,1,1} \\ \vdots \\ e_{27,2,1} \end{bmatrix}$

# OHP Picture 11

Final form:

$$y = X\beta + Zu + e$$

$$\begin{bmatrix} y_{12,1} \\ y_{11,1} \\ \vdots \\ y_{27,1} \end{bmatrix} = \begin{bmatrix} 1 & 1 & 0 \\ 1 & 1 & 0 \\ \vdots & \vdots & \vdots \\ 1 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} \mu \\ \beta_1 \\ \beta_2 \end{bmatrix} + \begin{bmatrix} u_1 \\ u_2 \\ \vdots \\ u_{27} \end{bmatrix} + e$$

From scalar notation:

$$2.61 = y_{12,1} = \mu + \beta_1 + u_{12} + e_{12,1}$$

$$= 1\mu + 1\beta_1 + 0\beta_2 + u_{12} + e_{12,1}$$

encoded into the dot product of the first row of matrix X times the vector  $\beta$ .

$$3.16 = y_{27,1} = 1\mu + 0\beta_1 + 1\beta_2 + u_{27} + e_{27,1}$$

# OHP Picture 12

□ Linear Mixed Effect Model all variances and covariances of random effects and all expected values must be specified.

□ Model:  $y = X\beta + Zu + e$

random →  $y$       fixed →  $X\beta$       random →  $Zu + e$

$$E[\beta] = \beta$$
$$\text{var}[\beta] = \mathbf{0}$$

Breeding values  $u$  are defined as deviations

$$\Rightarrow E[u] = \mathbf{0}$$

vector  $u = \begin{bmatrix} u_1 \\ \vdots \\ u_{27} \end{bmatrix}$        $\begin{bmatrix} 0 \\ \vdots \\ 0 \end{bmatrix}$

Residuals are also deviations

$$\Rightarrow E[e] = \mathbf{0}$$

$$\begin{aligned} \Rightarrow E[y] &= E[X\beta + Zu + e] = E[X\beta] + E[Zu] + E[e] \\ &= XE[\beta] + ZE[u] + E[e] \\ &= X\beta + Z\mathbf{0} + \mathbf{0} = X\beta \end{aligned}$$

# OHP Picture 13

□ Variances:

$$\text{var}(u) = G$$

↓  
variance-covariance matrix of random locally values

$$\text{var}(e) = R$$

↓  
variance-covariance matrix of random errors

$$\text{cov}(u, e^T) = 0 ; \text{cov}(\beta, u^T) = 0, \text{cov}(\beta, e^T) = 0$$

$$\Rightarrow \text{var}(y) = \text{var}(X\beta + Zu + e)$$

$$= \text{var}(X\beta) + \text{var}(Zu) + \text{var}(e)$$

$$= X \underbrace{\text{var}(\beta)}_{0} X^T + Z \text{var}(u) Z^T + \text{var}(e)$$

$$= ZGZ^T + R = V$$