### Genetic Covariances Between Animals

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# **BLUP Animal Model**

Traditional prediction of breeding values

- i.e. no genomic information available
- de-facto standard method

Model recap

$$y = X\beta + Zu + e$$

#### where

- y vector of length *n* of phenotypic information
- $\beta$  vector of length *p* of unknown fixed effects
- $X \quad n \times p$  incidence matrix
- *u* vector of length *q* of unknown random breeding values
- Z  $n \times q$  incidence matrix
- e vector of length n of unknown random residuals

# Example

Calf	Sire	Dam	Herd	WWG
3	1	2	1	4.5
4	1	NA	2	2.9
5	4	3	2	3.9
6	5	2	1	3.5

### Animal Model Setup

- Convert information from data into model
- Put observations in vector y

$$y = \begin{bmatrix} 4.5\\ 2.9\\ 3.9\\ 3.5 \end{bmatrix}$$

Fixed effects such as herd go in vector β and X links observations to components in β

$$X = \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 1 \\ 1 & 0 \end{bmatrix}, \ \beta = \begin{bmatrix} \beta_1 \\ \beta_2 \end{bmatrix}$$

# Breeding Values As Random Effects and Residuals

$$Z = \begin{bmatrix} 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \end{bmatrix}, \ u = \begin{bmatrix} u_1 \\ u_2 \\ u_3 \\ u_4 \\ u_5 \\ u_6 \end{bmatrix}, \ e = \begin{bmatrix} e_1 \\ e_2 \\ e_3 \\ e_4 \end{bmatrix}$$

Putting Everything Together

$$\begin{bmatrix} 4.5\\ 2.9\\ 3.9\\ 3.5\end{bmatrix} = \begin{bmatrix} 1 & 0\\ 0 & 1\\ 0 & 1\\ 1 & 0\end{bmatrix} \begin{bmatrix} \beta_1\\ \beta_2\end{bmatrix} + \begin{bmatrix} 0 & 0 & 1 & 0 & 0 & 0\\ 0 & 0 & 0 & 1 & 0 & 0\\ 0 & 0 & 0 & 0 & 1 & 0\\ 0 & 0 & 0 & 0 & 0 & 1\end{bmatrix} \begin{bmatrix} u_1\\ u_2\\ u_3\\ u_4\\ u_5\\ u_6\end{bmatrix} + \begin{bmatrix} e_1\\ e_2\\ e_3\\ e_4\end{bmatrix}$$

Solution with Mixed Model Equations

#### ► General form

$$\begin{bmatrix} X^T R^{-1} X & X^T R^{-1} Z \\ Z^T R^{-1} X & Z^T R^{-1} Z + G^{-1} \end{bmatrix} \begin{bmatrix} \hat{\beta} \\ \hat{u} \end{bmatrix} = \begin{bmatrix} X^T R^{-1} y \\ Z^T R^{-1} y \end{bmatrix}$$

• Assume  $R = I * \sigma_e^2$  and we set  $G = A * \sigma_u^2$ 

$$\begin{bmatrix} X^{T}X & X^{T}Z \\ Z^{T}X & Z^{T}Z + \lambda * A^{-1} \end{bmatrix} \begin{bmatrix} \hat{\beta} \\ \hat{u} \end{bmatrix} = \begin{bmatrix} X^{T}y \\ Z^{T}y \end{bmatrix}$$

with  $\lambda=\sigma_{e}^{2}/\sigma_{u}^{2}$ 

Components of Mixed Model Equations

### Numerator Relationship Matrix

- Only component missing in mixed model equations: matrix A
- A is called the numerator relationship matrix
- Properties of A

$$var(u) = G = A * \sigma_u^2$$

Meaning of var() for scalar variable x

Depending on type of argument to var(), the result is different
Scalar argument x, that means x is just a single number

$$var(x) = \sum (x - E[x])^2 f(x)$$

for a discrete random variable x, e.g. genotypic values V in single locus model.

$$var(x) = \int (x - E[x])^2 f(x) dx$$

for a continuous random variable x.

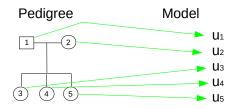
Meaning of *var*() for a vector *u* 

Assume that u is a vector with q elements

$$u = \begin{bmatrix} u_1 \\ u_2 \\ \dots \\ u_q \end{bmatrix}$$

Then var(u) is a q × q variance-covariance matrix with a structure shown on the next slide

# Meaning of A



#### Variance-Covariance

	U1	U2	Uз	U4	U5
Uı	var(u1)	COV(U1,U2)	cov(u1,u3)	COV(U1,U4)	cov(u1,u5)
U2		var(u2)	COV(U2,U3)	COV(U2,U4)	COV(U2,U5)
Uз			var(u3)	COV(U3,U4)	cov(u3,u5)
$U_4$				var(u4)	COV(U4,U5)
<b>U</b> 5					var(u₅)

## Elements of A

- Remember:  $var(u) = G = A * \sigma_u^2$
- Diagonal elements (A)<sub>ii</sub> = 1 + F<sub>i</sub> where F<sub>i</sub>: inbreeding coefficient of i
- Offdiagonal elements  $(A)_{ij} = cov(u_i, u_j)/\sigma_u^2$
- Symmetric
- Definition leads to recursive algorithm for computing components of A

## Example

Elements of G are computed as

 Animal 1 has unknown parents and is assumed to show no inbreeding (parents are not related)

$$var(u_1) = (1 + F_1) * \sigma_u^2 = \sigma_u^2$$

Animal 2 has unknown parents and is not related to animal 1

$$cov(u_1,u_2)=0$$

Animal 3 has parents 1 and 2

$$cov(u_1, u_3) = cov\left(u_1, \left[\frac{1}{2}(u_1 + u_2) + m_3\right]\right) = \frac{1}{2}\sigma_u^2$$